# Structural Optimization Methods and Techniques to Design Efficient Car Bodies

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### Abstract

Global and intense competition in the automobile market impose automobile companies and their engineers the need to design and build vehicles that perform better than their previous models, that are lighter, more fuel efficient, quieter, pollute less and yet are cheaper to manufacture. In this paper, different optimization methods and techniques that can be used to address some of these issues are discussed. Methods such as sizing, shape, topology, topometry, topography and freeform optimization are described and examples on their use are presented. Techniques that allow reinforcing structures, find load paths, find best location of welds are discussed. The paper will provide bibliographical references that show what currently is being used in the automobile industry. The paper will show that today optimization methods are mature and can be used at different stages of the design process of vehicles.

## Introduction

For most of the history of design, designers have relied on their intuition and/or improving previous models to design their new models. Most designs could not be tested as analytical formulas could not be used for real problems. Only in the last few decades finite element analysis has been used. Optimization as a design tool only in the recent years has started to be used more commonly in the marketplace. Structural optimization software has only been available in the last two decade, but some of the optimization that software offers today did not even exist 10 years ago. The novelty of these techniques results that the potential of structural optimization is not yet fully utilized. In this paper we will discuss some examples that show what is possible for car body design. First we will summarize the general methods and then we will show examples for car body design.

## **The Optimization Problem**

The optimization problem can be stated as:

$$\begin{split} & \underset{x_{i}}{Min} F(x_{1}, x_{2}, ..., x_{n}) \\ & \text{such that:} \\ & g_{j}(x_{1}, x_{2}, ..., x_{n}) \leq 0; \quad j = 1, m \\ & x_{l}_{i} \leq x_{i} \leq xu_{i}; \quad i = 1, n \end{split}$$

#### Fig 1 – Optimization Problem Statement

where F is the objective function, gj are the constraints, xi are the design variables and xl<sub>i</sub> and xu<sub>i</sub> the side constraints.

#### **Objective Function**

Any of the considered responses can be used as the objective function for minimization or maximization. Often mass, strain energy or frequencies are used as objective functions.

#### **Constraints**

Any of the considered responses can be constrained to user-specified limits. Typical constraints are mass, stress, displacements, and dynamic displacements, velocities and accelerations.

#### Design Variables

Design variables are parameters that can change directly or indirectly dimension of elements, grid locations and/or material properties.

## **Structural Optimization**

Structural optimization is a kind of optimization used to improve structures. In structural optimization the responses come from finite element results and the design variables correspond to parameters that describe the structure.

## **Technology background**

The structural optimization problem is solved using the approximation concepts approach. In this approach, an approximate analysis model is created and optimized at each design cycle. The design solution of the approximate optimization is then used to update the finite element model, and a full system analysis is performed to create the next approximate analysis model. The sequence of design cycles continues until the approximate optimum design converges to the actual optimum design. In the mid-seventies Schmit et al. introduced approximation concepts for traditional structural optimization [1-2]. These concepts, in the eighties and early nineties, were refined to improve the quality of approximations [3-6]. The approximate problem is solved using either the BIGDOT [7-8] or DOT [9] optimizers. The purpose of using the approximation concepts approach is to reduce the number of design cycles to reduce time. With these approximations a good engineering answer can be typically found in 10 design cycles. This approximation are built-in in the Genesis software [10] which is the program used in this paper.

## **Structural Optimization Types**

Several types of structural optimization methods that are available can be used to design car bodies. We can classify them by the type of design variables associated to them. A list of the different types is as follows: topology, sizing, topometry, shape, topography and freeform. Next a brief description of each type is presented:

### **Topology Optimization**

In topology optimization, the design variables correspond to the element volume fractions. The volume fraction designs simultaneously the material properties E (modulus of elasticity) and density with the purpose of getting a 0-1 answer in order to identify the key elements to keep and the rest to discard [11].

#### Sizing Optimization

In sizing optimization, the element cross-sectional dimensions are typically used as design variables. In car bodies the most important design variable type is the thickness of shell elements [12].

#### **Topometry Optimization**

Topometry optimization is a generalization of sizing optimization. Unlike size optimization, where all elements associated to a property data entry are designed with the same values, in topometry optimization each element is designed independently [12].

#### Shape Optimization

In shape optimization, scale factors of perturbation vectors are the design variables. The perturbation vectors are input directly or by providing basis vectors. Basis vectors contain alternative grid locations that represent candidate designs. When the user provides basis vectors, they can be internally converted into perturbation vector by performing a vectorial difference between the provided basis vector and the original grid locations [13]. Currently, GENESIS contains three methods to automate creation of basis or perturbation vectors: the GRID basis vector method, the natural basis vector method, and the DOMAIN method [14].

#### **Topography Optimization**

Topography optimization is a special case of shape optimization. In this type of optimization, the program automatically generates perturbation vectors that are: either perpendicular to the designable region or in a given direction [15].

#### Freeform Optimization

Freeform optimization is another special case of shape optimization. In this type of optimization, the program splits any given perturbation into multiple perturbations on a grid by grid basis. This increases the variability of the design space when compared with traditional shape optimization. Freeform unlike topography optimization can be applied to any type of elements. Freeform can be used to design rib on solid components and design bead patterns of constant or variable height [16].

## **Use of Structural Optimization**

Form follows function is a principle associated with modern architecture and industrial design which has been present for more than a century. The principle is that the shape of a building or an object should be primarily based upon its intended function or purpose. Specifically for automobile and car bodies this principle holds. However, quite often designers are not free to just design, they have to keep in mind what methods of fabrications exist and if they use optimization software they need to know which of them to use. So therefore it is important to link the different types of structural optimization types with the different manufacturing types.

SO Types	Stamping	Casting	Extrusion	Tailor Welded
Sizing	Yes	-	-	Yes
Shape	Yes	Yes	-	-
Topology	Yes	Yes	Yes	-
Topometry	-	Yes	-	Yes
Topography	Yes	Yes	-	-
Freeform	Yes	Yes	-	-

Table 1 – Types of Structural Optimization versus Manufacturing Types

Table 1 shows typical optimization methods used for typical manufacturing processes. However, creativity of the users and new functions that emerge can change this classification.

## **Techniques to Design Car Bodies**

Car bodies represent about 20% of the total weight of a typical car and a typical car body weighs about 360 kg [17]. Studies shows that saving 1% mass of a car body can save 0.7% energy [18], therefore, it is important that all techniques or methods can consider mass in the objective or constraints. Car bodies can be designed directly using sizing or shape optimization or with steps using methods that are more adequate for preliminary design such as topology, topography, topometry and freeform. Optimization methods allow improving stiffness and Strength. Bonding (Spot Welding) components can be also improved with optimization; the following table shows what types of optimization are appropriated to some design tasks:

SO Types	Preliminary	Stiffness	Strength	Final Design	Reinforcement	Bonding
Sizing	Yes	Yes	Yes	Yes	Yes	Occasionally
Shape	Yes	Yes	Yes	Yes	-	-
Topology	Yes	Yes	-	Occasionally	Yes	Yes
Topometry	Yes	Yes	-	Occasionally	Yes	Yes
Topography	Yes	Yes	-	Occasionally	Yes	-
Freeform	Yes	Yes	-	Occasionally	Yes	-

Table 2 – Types of Structural Optimization versus Common Car Bodies Optimization Tasks

Table 2 shows some commonly used tasks for each type of optimization.

## **Trade-off studies versus Direct Optimization**

A Trade-off curve of maximum performance target versus mass is commonly used to decide what design is good and affordable at the same time. To fill a performance versus mass curve, the user can solve a series of optimization tasks in which each of them is to maximize the performance subject to a different mass constraint. Alternatively, the user can minimize mass using performance targets as constraints. In this latter procedure there is no trade-off but as long as all targets are satisfied the user knows what the minimum mass is for that.

# **Topology Optimization Method**

Topology optimization is typically used either in early stages of the design or later for reinforcement. It can also be used to find optimal location of welds. Because topology optimization can get the stiffest structure possible, engineers quite often use topology to design for stiffness.

### Topology Optimization for Preliminary Design

Topology optimization is used for preliminary design because it can give a good idea what is the load path and allows to define the basic architecture of the car vehicle. The following example is from reference [19]. In this example 10 different load cases (with inertia relief) were used to find the optimal topology. Figure 2 shows the topology results..

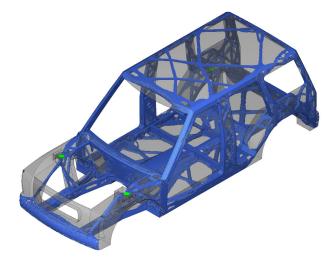


Fig 2 – Topology Optimization of Vehicle

### Topology Optimization to Reinforce Structures

If a design is completed; but if it is desirable to increase a particular performance target without adding too much mass, topology optimization can be used. Next two techniques that are useful are described:

Second Layer Method - Allows locating the best locations to reinforce a car body that was already designed [20].

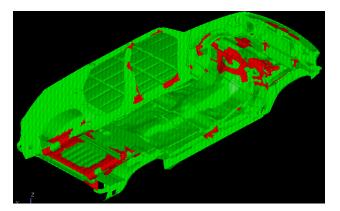


Fig 3 - Topology Optimization of Vehicle. Red Areas Show Optimal Areas to Reinforce

<u>Autorib Method</u> – Ribs are effective ways to add stiffness to certain components. This method allows to create ribs around areas of interest and then designed with topology [10]

# Sizing Optimization Method

Sizing optimization can be used to find the optimal thickness distribution on a property by property basis. Typical problems can minimize mass subject to stress, natural frequencies and displacements constraints.

### Sizing Optimization for Torsional Stiffness Maximization

In this example, sizing optimization was used to find the optimal thickness distribution to reinforce a car body. The car model has 245,344 shell elements designing 51 PSHELL data entries. The objective function of the problem consists of maximizing the torsion stiffness of the car. There are 51 design variables. The study allows the thickness to grow and/or to reduce a certain percentage. A simple case was studied where the mass was allowed to increase 2%.

Figure 4 shows the thickness distribution using 6 views. Red represents the largest thickness, blue represents the smaller thickness.

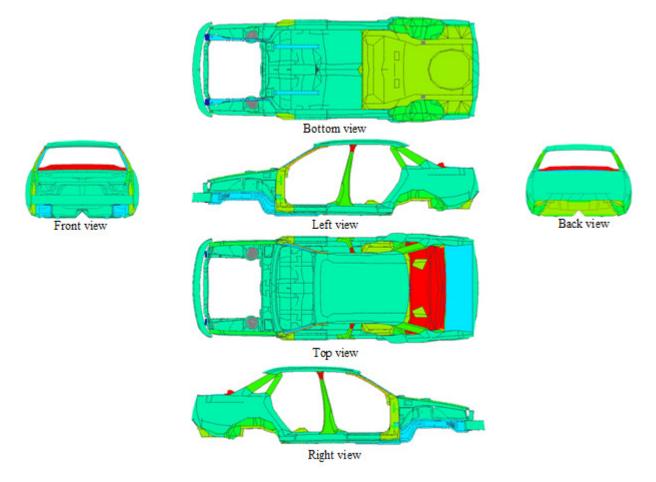


Fig 4 – Thickness Distribution using Sizing Optimization

### **Results**

The torsional stiffness was increased from 7369Nm/deg to 10,350Nm/deg giving a 40% gain. The mass increased from 288.5 kg to 294.2 a 1.99% increase.

# **Topometry Optimization Method**

Topometry optimization can be used to find the optimal thickness distribution on element by element basis. Typical problems can be maximizing static or dynamic stiffness subject to mass and displacements constraints.

#### Topometry Optimization for Torsional Stiffness Maximization

In this example, topometry optimization was used to find the optimal thickness distribution to reinforce a car body. The car model has 245,344 shell elements designing 51 PSHELL data entries. The objective function of the problem consists of maximizing the torsion stiffness of the car. In this case due to symmetry 122,756 design variables were used. The study allows the thickness to grown up tp 1 mm to study best places to reinforce. A mass constraint allowed to it by increase 2%.

Figure 5 shows the thickness distribution using 6 views. Red represents the largest thickness, blue represent the smaller thickness.

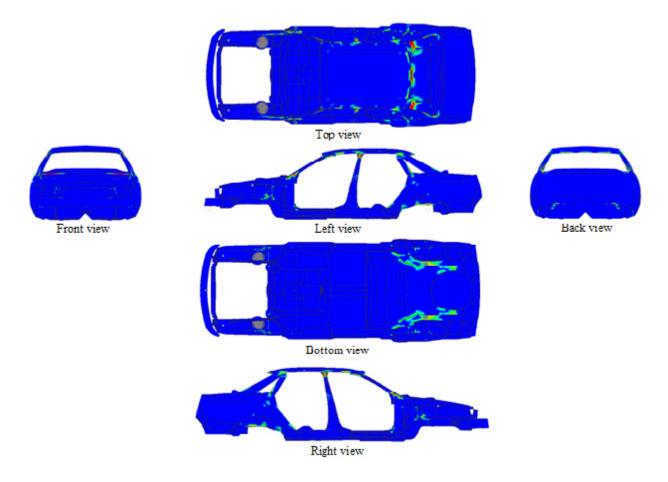


Fig 5 – Optimal Places to Reinforce a Car Body using Topometry Optimization

### Results

The torsional stiffness was increased from 7369Nm/deg to 11,474Nm/deg giving a 56% gain. The mass increased from 288.5 kg to 293.4 a 1.7% increase.

# **Freeform Optimization Method**

Freeform optimization can be used to find the optimal location of bead pattern. In car bodies it allows to increase the stiffness of the vehicle without adding too much mass.

### Freeform Optimization for Torsional Stiffness maximization

In this example, freeform optimization was used to find the best places to add beads to increase the torsional stiffness of the car body. The car model has 228,883 grids. The objective function of the problem consists of maximizing the torsion stiffness of the car. The study allowed only 1% of the grids to move so that a reduced and more practical number of beads is actually created. A mass constraint allowed to it by increase 2%. In this case due to symmetry 127,669 design variables were used to design the grid location. The design variables correspond, in this case, to scale factors of perturbation that are normal to the surface of the car body. Figure 6 shows the perturbation as small arrows. Reference [21] presented the idea used in this example for topography optimization.

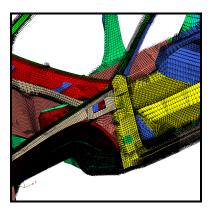
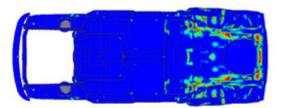
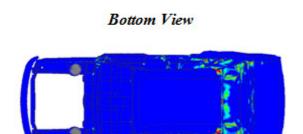


Fig 6 –Perturbation Vectors that Define the Design Space

Figure 7 shows the bead pattern in colors. Red represents the largest height of the bead, blue represents no movement of grids.





Top View

Fig 7– Freeform Optimization Results Shows the Optimal Place to ad Bead Pattern

### <u>Results</u>

The torsional stiffness was increased from 7369Nm/deg to 11,663Nm/deg giving a 58% gain. The mass increased from 288.5 kg to 289.2 which represent a 0.2% increase.

# **Comparison of Different Optimization Types**

We solved the same problem using different techniques to study what kind of gain we can get by using them. The following chart shows the results for several cases studied:

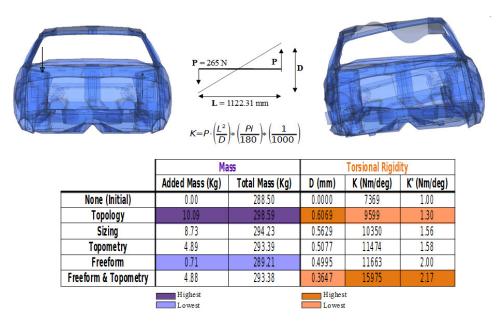


Fig 8 – Results of Stiffness Optimization using Different Structural Optimization Types

Figure 9 shows the type of gain versus torsion stiffness:

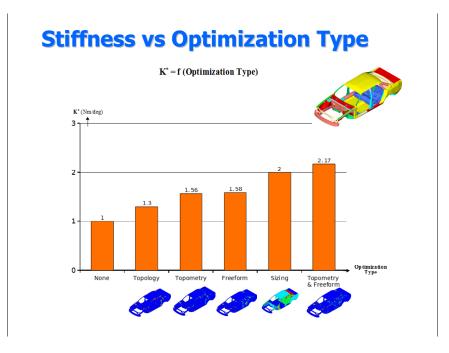


Fig 9 – Results of Stiffness Optimization using Different Structural Optimization Types

Figure 9 shows that, using structural optimization, the torsional stiffness of a car body can be greatly increased without adding too much mass. This was observed for all types of optimizations and especially for freeform. It should be noted that this Figure is not intended for comparing the methods against each other as the used mass was not necessarily the same in each case. Reference [12] provides a case study that compares the effectiveness of topology, sizing, topometry and shape using same mass on a simple structure.

Figure 10 shows the results and the number of design variables of the studies problems:

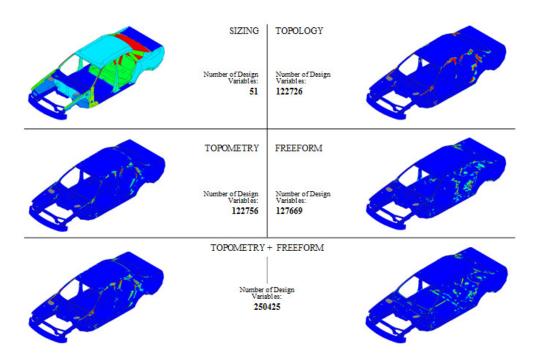


Fig 10 – Results of Stiffness Optimization using Different Structural Optimization Types

## **Topography Optimization Method**

Topography optimization is typically used in early stages of the design. It is typically used to find optimal locations of bead patterns that allow reinforcing panel that are not so stiffen enough like automobile hoods. Topography optimization can also be used in floor panel, trunk and parts that are not visible.

#### Topography Optimization for Reinforcement of Car Hood

Figure 11 shows the results of topography optimization. In the picture bellow red indicates the maximum height of the beads generated by optimization, blue means that grids are not moved. Green indicates lesser movements.

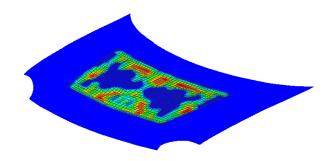


Fig 11 – Bead Pattern Results using Topography Optimization

## **Publications Describing Car Bodies Design**

References [23-32] provide additional examples of car body designs. They can be helpful to understand the usage of structural optimization in industry.

## Spot Weld Optimization of Car Body Using Sizing Optimization

This problem is presented in Ref. 22 so here we just give the key features of the problem. The requirements of the problem were to find a trade-off table for the optimal locations of spot welds. The objective function of each case was to maximize the sum of the first bending and first torsional frequencies. The constraint of the problem was the number of welds to keep. The problem was solved using sizing optimization with 4316 design variables. The variables designed 4316 CVECTOR elements that modeled spot-welds. This problem was optimized six times to study the effect of taking out different numbers of welds. Table 3 shows the results for all optimization cases and the case where all welds were used (100%). This table gives the designer trade-off information that helps to study the influence of the number of welds on the rigidity of the car body.

Quantity of kept welds (%)	First torsional frequency (Hz)	First bending frequency (Hz)	Sum of two requencies (Hz)
30	24.983	35.100	60.083
40	26.662	37.330	63.992
50	29.831	40.755	70.586
60	30.499	42.100	72.599
70	31.312	44.947	76.259
80	31.762	5.718	77.480
100	31.962	46.185	78.147

#### Table 3. Relation Between Rigidity and Number of Welds

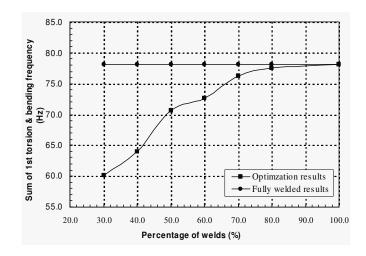


Fig 12 – Parentage of Weld versus Frequencies



Fig 13 – Optimal Weld Location, 70% Kept Welds and 30% Discarded

## Conclusions

Several methods to perform structural optimization have been presented. The use of these methods allows designers to find efficient and innovative designs which can not be achieved by traditional manual methods. The paper showed that using structural optimization, the stiffness of a car body can be greatly increased without adding too much mass. The methods presented allow the designer to explore a larger design space and improve the usage of material and/or minimize mass.

## Acknowledgments

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